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Uncertainty estimation for environmental predictions: the BLUECAT approach and software Session HS4.3

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The quest for certainty blocks the search for meaning. Uncertainty is the very condition to impel man to unfold his powers. Erich Fromm (1900-1980)

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EGU 2025 General Assembly — Alberto Montanari (presentation available at www.albertomontanari.it)



What is **BLUECAT**

ATTER STUDIORUM www.albertomontanari.it/bluecat

- What is Bluecat
- Bluecat workflow
- Assumptions
- Theory
- Testing
- Software and take home message

• BLUECAT is a method for estimating uncertainty of predictions provided by a deterministic **calibrated** model;

Koutsoyiannis and Montanari (2022) & Montanari and Koutsoyiannis (2024).

- BLUECAT is ready to use, with a software in Python and R that comes with help facilities and examples of application (https://github.com/albertomontanari)
- BLUECAT is accompanied by procedures for rigorously testing the reliability of the estimated uncertainty bands.



Γ	Water Resources Research
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	Bluecat: A Local Uncertainty Estimator for Deterministic Simulations and Predictions
	D. Koutsoyiannis, A. Montanari 📷





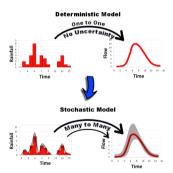


BLUECAT: looking for simplicity and operational efficiency

What is Bluecat

BLUECAT transforms a deterministic prediction model into a stochastic prediction model.

- From a point prediction we obtain the probability distribution of the predictand. From the above probabil distribution we estimate the average (or median) predic along with its confidence band for an assigned confiden level.
 - BLUECAT is more than an uncertainty assessment method it is rather a new prediction model with a stochastic structure. BLUECAT can be applied in conjunction with any deterministic prediction model.





BLUECAT: looking for simplicity and operational efficiency

What is Bluecat

Bluecat workflow

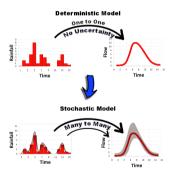
Assumptions

Theory

Testing

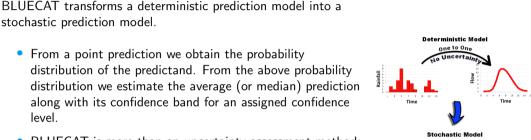
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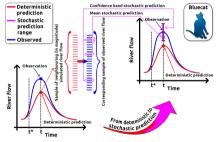
What is

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- A point prediction is obtained with a deterministic model.
- A sample of neighbouring (in magnitude to the point prediction) simulated river flows is collected from the calibration period.
- A corresponding sample of observed river flows is collected. This is used to estimate (from data) the probability distribution of the predictand.
- Mean (or median) value is extracted along with the confidence bands.
- The stochastic prediction is obtained along with uncertainty assessment.





BLUECAT: assumptions

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Software and take home message **Note**: in what follows, deterministic and stochastic model are D-model and S-model, respectively. BLUECAT assumptions:

- The stochastic processes describing the modelled variables are stationary during the calibration and application period. Non-stationarity can be accounted for by using non-stationary D-models.
- The calibration data set is extended enough to ensure that sufficient information is available to upgrade the D-model into the S-model.
- Uncertainty is not subdivided in different components as BLUECAT is assumed to automatically incorporate all types, including the uncertainty in input data and parameters, for which no particular provision is necessary.

Why BLUECAT? "Brisk Local Uncertainty Estimator for generiC simulations And predic-Tions"

BLUECAT refers to the pop-art by Andy Warhol (1928–1987), a success creation stimulated by a simple idea that gives a feeling of positive thinking and optimism.



BLUECAT: a bit of theory

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Software and take home message To advance from the D-model to the S-model in we need to specify the conditional distribution:

$$F_{q|Q}(q|Q) = P\left\{\underline{q} \leq q|\underline{Q} = Q
ight\},$$

where q and Q are concurrent observed and simulated flow, respectively, and stochastic variables are underlined.

If Q and q are concurrent time series, each of size n, and if $Q_{(i:n)}$ is the *i*th smallest value in Q and $q_{(j:n)}$ is the *j*th smallest value in q, then the approximations $F_Q(Q_i) \approx i/n$ and $F_q(q_j) \approx j/n$ can be used. After mathematical development we we prove that $F_{q|Q}$ can be obtained by minimizing the quantity

$$A := \sum_{j=1}^{n} (B_j - j)^2 = \sum_{j=1}^{n} \left(\sum_{i=1}^{n} F_{q|Q} \left(q_{(j:n)} | Q_{(i:n)} \right) - j \right)^2,$$

therefore getting the desired conditional distribution which leads to the formulation of the S-model corresponding to the D-model.



Hypothesis testing

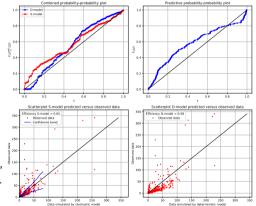
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- Testing stochastic physically-based assumptions through validation of the confidence band of the prediction.
- Verification of the reliability of uncertainty assessment.
- The only solution to quantitative testing of uncertainty assessment is comparison with observed data.
- Combined probability-probability plot (CPP), Predictive probability-probability plot (PPP).
- Embedded in the BLUECAT software.





Ensemble simulation with BLUECAT

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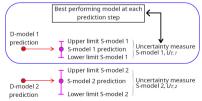
Theory

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Software and take home message

- Multimodel simulation is attractive (for example, a rainfall-runoff model with different parameters for different regimes).
- Two challenges: (a) how to combine different predictions (Bayesian averaging is an option) (b) how to estimate uncertainty for the obtained combination (remember: the pure ensemble spread does not suffice to provide a comprehensive estimate of uncertainty).
- BLUECAT: uncertainty of each model estimated at each prediction step as a criteria to select the optimal ensemble member (M&K, 2024).

A single model prediction corresponding to the least uncertain ensemble member, that is identified through a proper measure, is picked up at each prediction step.



BLUECAT software (www.albertomontanari.it/bluecat)

Software and take home message

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Bluecat Home Page Uncertainty assessment for hydrological models (with software)

Software are accompanied by embedded help and examples of applications for full reproducibility.



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